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# A generalization of Hukuhara difference for interval and fuzzy arithmetic

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**Abstract.** We propose a generalization of the Hukuhara difference. First, the case of compact convex sets is examined; then, the results are applied to generalize the Hukuhara difference of fuzzy numbers, using their compact and convex level-cuts. Finally, a similar approach is suggested to attempt a generalization of division for real intervals.

# 1 General setting

We consider a metric vector space X with the induced topology and in particular the space  $X = \mathbb{R}^n$ ,  $n \geq 1$ , of real vectors equipped with standard addition and scalar multiplication operations. Following Diamond and Kloeden (see [3]), denote by  $\mathcal{K}(X)$  and  $\mathcal{K}_C(X)$  the spaces of nonempty compact and compact convex sets of X. Given two subsets  $A, B \subseteq X$  and  $k \in \mathbb{R}$ , Minkowski addition and scalar multiplication are defined by  $A+B = \{a+b|a \in A, b \in B\}$  and  $kA = \{ka|a \in A\}$ and it is well known that addition is associative and commutative and with neutral element  $\{0\}$ . If k = -1, scalar multiplication gives the opposite -A = $(-1)A = \{-a|a \in A\}$  but, in general,  $A+(-A) \neq \{0\}$ , i.e. the opposite of A is not the inverse of A in Minkowski addition (unless  $A = \{a\}$  is a singleton). Minkowski difference is  $A - B = A + (-1)B = \{a - b|a \in A, b \in B\}$ . A first implication of this fact is that, in general, even if it true that  $(A + C = B + C) \iff A = B$ , addition/subtraction simplification is not valid, i.e.  $(A + B) - B \neq A$ .

To partially overcome this situation, Hukuhara [4] introduced the following H-difference:

$$A \odot B = C \iff A = B + C \tag{1}$$

and an important property of  $\bigcirc$  is that  $A \bigcirc A = \{0\}, \forall A \in \mathbb{R}^n$  and  $(A+B) \bigcirc B = A, \forall A, B \in \mathbb{R}^n$ ; H-difference is unique, but a necessary condition for  $A \bigcirc B$  to exist is that A contains a translate  $\{c\} + B$  of B. In general,  $A - B \neq A \odot B$ .

From an algebraic point of view, the difference of two sets A and B may be interpreted both in terms of addition as in (1) or in terms of negative addition, i.e.

$$A \boxminus B = C \iff B = A + (-1)C \tag{2}$$

where (-1)C is the opposite set of C. Conditions (1) and (2) are compatible each other and this suggests a generalization of Hukuhara difference: **Definition 1.** Let  $A, B \in \mathcal{K}(\mathbb{X})$ ; we define the generalized difference of A and B as the set  $C \in \mathcal{K}(\mathbb{X})$  such that

$$A \ominus_g B = C \iff \begin{cases} (i) & A = B + C \\ or (ii) & B = A + (-1)C \end{cases}$$
(3)

**Proposition 1.** (Unicity of  $A \odot_g B$ ) If  $C = A \odot_g B$  exists, it is unique and if also  $A \odot B$  exists then  $A \odot_g B = A \odot B$ .

Proof. If  $C = A \odot_g B$  exists in case (i), we obtain  $C = A \odot B$  which is unique. Suppose that case (ii) is satisfied for C and D, i.e. B = A + (-1)C and B = A + (-1)D; then  $A + (-1)C = A + (-1)D \Longrightarrow (-1)C = (-1)D \Longrightarrow C = D$ . If case (i) is satisfied for C and case (ii) is satisfied for D, i.e. A = B + C and B = A + (-1)D, then  $B = B + C + (-1)D \Longrightarrow \{0\} = C - D$  and this is possible only if  $C = D = \{c\}$  is a singleton.

The generalized Hukuhara difference  $A \ominus_g B$  will be called the <u>gH-difference</u> of A and B.

Remark 1. A necessary condition for  $A \odot_g B$  to exist is that either A contains a translate of B (as for  $A \odot B$ ) or B contains a translate of A. In fact, for any given  $c \in C$ , we get  $B + \{c\} \subseteq A$  from (i) or  $A + \{-c\} \subseteq B$  from (ii).

Remark 2. It is possible that A = B+C and B = A+(-1)C hold simultaneously; in this case, A and B translate into each other and C is a singleton. In fact, A = B+C implies  $B + \{c\} \subseteq A \ \forall c \in C$  and B = A+(-1)C implies  $A - \{c\} \subseteq B$  $\forall c \in C$  i.e.  $A \subseteq B + \{c\}$ ; it follows that  $A = B + \{c\}$  and  $B = A + \{-c\}$ . On the other hand, if  $c', c'' \in C$  then  $A = B + \{c'\} = B + \{c''\}$  and this requires c' = c''.

*Remark 3.* If  $A \ominus_g B$  exists, then  $B \ominus_g A$  exists and  $B \ominus_g A = -(A \ominus_g B)$ .

**Proposition 2.** If  $A \ominus_g B$  exists, it has the following properties:

1)  $A \odot_g A = \{0\};$ 2)  $(A + B) \odot_g B = A;$ 3) If  $A \odot_g B$  exists then also  $(-B) \odot_g (-A)$  does and  $-(A \odot_g B) = (-B) \odot_g (-A);$ 4)  $(A - B) + B = C \iff A - B = C \odot_g B;$ 5) In general, B - A = A - B does not imply A = B; but  $(A \odot_g B) = (B \odot_g A) = C$ if and only if  $C = \{0\}$  and A = B;6) If  $B \odot_g A$  exists then either  $A + (B \odot_g A) = B$  or  $B - (B \odot_g A) = A$  and both equalities hold if and only if  $B \odot_g A$  is a singleton set.

Proof. Properties 1 and 5 are immediate. To prove 2) if  $C = (A+B) \ominus_g B$  then either A+B = C+B or B = (A+B) + (-1)C = B + (A+(-1)C); in the first case it follows that C = A, in the second case  $A + (-1)C = \{0\}$  and A and Care singleton sets so A = C. To prove the first part of 3) let  $C = A \ominus_g B$  i.e. A = B + C or B = A + (-1)C, then -A = -B + (-C) or -B = -A - (-C)and this means  $(-B) \odot_g (-A) = -C$ ; the second part is immediate. To see the first part of 5) consider for example the unidimensional case  $A = [a^-, a^+]$ ,  $B = [b^-, b^+]$ ; equality A - B = B - A is valid if  $a^- + a^+ = b^- + b^+$  and this does not require A = B (unless A and B are singletons). For the second part of 5), from  $(A \odot_g B) = (B \odot_g A) = C$ , considering the four combinations derived from (3), one of the following four case is valid: (A = B + C and B = A + C)or (A = B + C and A = B - C) or (B = A + (-1)C and B = A + C) or (B = A + (-1)C and A = B + (-1)C); in all of them we deduce  $C = \{0\}$ . To see 6), consider that if  $(B \odot_g A)$  exists in the sense of (i) the first equality is valid and if it exists in the sense of (ii) the second one is valid.

If  $\mathbb{X} = \mathbb{R}^n$ ,  $n \geq 1$  is the real *n*-dimensional vector space with internal product  $\langle x, y \rangle$  and corresponding norm  $||x|| = \sqrt{\langle x, x \rangle}$ , we denote by  $\mathcal{K}^n$  and  $\mathcal{K}^n_C$ the spaces of (nonempty) compact and compact convex sets of  $\mathbb{R}^n$ , respectively. If  $A \subseteq \mathbb{R}^n$  and  $\mathcal{S}^{n-1} = \{u|u \in \mathbb{R}^n, ||u|| = 1\}$  is the unit sphere, the support function associated to A is

$$s_A : \mathbb{R}^n \longrightarrow \mathbb{R}$$
 defined by  
 $s_A(u) = \sup\{\langle u, a \rangle | a \in A\}, u \in \mathbb{R}^n.$ 

If  $A \neq \emptyset$  is compact, then  $s_A(u) \in \mathbb{R}$ ,  $\forall u \in S^{n-1}$ . The following properties are well known (see e.g. [3] or [5]):

- Any function  $s : \mathbb{R}^n \longrightarrow \mathbb{R}$  which is continuous, positively homogeneous  $s(tu) = ts(u), ), \forall t \geq 0, \forall u \in \mathbb{R}^n$  and subadditive  $s(u' + u'') \leq s(u') + s(u''), \forall u', u'' \in \mathbb{R}^n$  is a support function of a compact convex set; the restriction  $\hat{s}$  of s to  $\mathcal{S}^{n-1}$  is such that  $\hat{s}(\frac{u}{||u||}) = \frac{1}{||u||}s(u), \forall u \in \mathbb{R}^n, u \neq 0$  and we can consider s restricted to  $\mathcal{S}^{n-1}$ . It also follows that  $s : \mathcal{S}^{n-1} \longrightarrow \mathbb{R}$  is a convex function.
- If  $A \in \mathcal{K}_C^n$  is a compact convex set, then it is characterized by its support function and

$$A = \{x \in \mathbb{R}^n | \langle u, x \rangle \le s_A(u), \, \forall u \in \mathbb{R}^n\} = \{x \in \mathbb{R}^n | \langle u, x \rangle \le s_A(u), \, \forall u \in \mathcal{S}^{n-1}\}$$

- For  $A, B \in \mathcal{K}^n_C$  and  $\forall u \in \mathcal{S}^{n-1}$  we have  $s_{\{0\}}(u) = 0$  and

$$A \subseteq B \Longrightarrow s_A(u) \le s_B(u); A = B \iff s_A = s_B,$$
  
$$s_{kA}(u) = ks_A(u), \forall k \ge 0; \quad s_{kA+hB}(u) = s_{kA}(u) + s_{hB}(u), \forall k, h \ge 0$$

and in particular

$$s_{A+B}(u) = s_A(u) + s_B(u)$$

- If  $s_A$  is the support function of  $A \in \mathcal{K}_C^n$  and  $s_{-A}$  is the support function of  $-A \in \mathcal{K}_C^n$ , then  $\forall u \in \mathcal{S}^{n-1}, s_{-A}(u) = s_A(-u);$ 

- If v is a measure on  $\mathbb{R}^n$  such that  $v(\mathcal{S}^{n-1}) = \int_{\mathcal{S}^{n-1}} v(du) = 1$ , a distance is defined by

$$\rho_2(A,B) = ||s_A - s_B|| = \left(n \int_{\mathcal{S}^{n-1}} [s_A(u) - s_B(u)]^2 v(du)\right)^{\frac{1}{2}};$$

- The Steiner point of  $A \in \mathcal{K}_C^n$  is defined by  $\sigma_A = n \int_{\mathcal{S}^{n-1}} u s_A(u) v(du)$  and  $\sigma_A \in A$ .

We can express the generalized Hukuhara difference (gH-difference) of compact convex sets  $A, B \in \mathcal{K}_C^n$  by the use of the support functions. Consider  $A, B, C \in \mathcal{K}_C^n$  with  $C = A \ominus_g B$  as defined in (3); let  $s_A, s_B, s_C$  and  $s_{(-1)C}$  be the support functions of A, B, C, and (-1)C respectively. In case (i) we have  $s_A = s_B + s_C$  and in case (ii) we have  $s_B = s_A + s_{(-1)C}$ . So,  $\forall u \in S^{n-1}$ 

$$s_C(u) = \begin{cases} s_A(u) - s_B(u) & \text{in case } (i) \\ s_B(-u) - s_A(-u) & \text{in case } (ii) \end{cases}$$

i.e.

$$s_C(u) = \begin{cases} s_A(u) - s_B(u) & \text{in case } (i) \\ s_{(-1)B}(u) - s_{(-1)A}(u) & \text{in case } (ii) \end{cases}.$$
 (4)

Now,  $s_C$  in (4) is a correct support function if it is continuous, positively homogeneous and subadditive and this requires that, in the corresponding cases (i) and (ii),  $s_A - s_B$  and/or  $s_{-B} - s_{-A}$  be support functions, assuming that  $s_A$ and  $s_B$  are.

Consider  $s_1 = s_A - s_B$  and  $s_2 = s_B - s_A$ . Continuity of  $s_1$  and  $s_2$  is obvious. To see their positive homogeneity let  $t \ge 0$ ; we have  $s_1(tu) = s_A(tu) - s_B(tu) = ts_A(u) - ts_B(u) = ts_1(u)$  and similarly for  $s_2$ . But  $s_1$  and/or  $s_2$  may fail to be subadditive and the following four cases, related to the definition of gH-difference, are possible.

**Proposition 3.** Let  $s_A$  and  $s_B$  be the support functions of  $A, B \in \mathcal{K}_C^n$  and consider  $s_1 = s_A - s_B$ ,  $s_2 = s_B - s_A$ ; the following four cases apply:

1. If  $s_1$  and  $s_2$  are both subadditive, then  $A \ominus_g B$  exists; (i) and (ii) are satisfied simultaneously and  $A \ominus_g B = \{c\}$ ;

2. If  $s_1$  is subadditive and  $s_2$  is not, then  $C = A \ominus_g B$  exists, (i) is satisfied and  $s_C = s_A - s_B$ ;

3. If  $s_1$  is not subadditive and  $s_2$  is, then  $C = A \ominus_g B$  exists, (ii) is satisfied and  $s_C = s_{-B} - s_{-A}$ ;

4. If  $s_1$  and  $s_2$  are both not subadditive, then  $A \ominus_q B$  does not exist.

Proof. In case 1. subadditivity of  $s_1$  and  $s_2$  means that,  $\forall u', u'' \in S^{n-1}$ 

$$s_1: s_A(u'+u'') - s_B(u'+u'') \le s_A(u') + s_A(u'') - s_B(u') - s_B(u'') \text{ and}$$
  
$$s_2: s_B(u'+u'') - s_A(u'+u'') \le s_B(u') + s_B(u'') - s_A(u') - s_A(u'');$$

it follows that

$$s_A(u'+u'') - s_A(u') - s_A(u'') \le s_B(u'+u'') - s_B(u') - s_B(u'') \text{ and}$$
  
$$s_B(u'+u'') - s_B(u') - s_B(u'') \le s_A(u'+u'') - s_A(u') - s_A(u'')$$

so that equality holds

$$s_B(u'+u'') - s_A(u'+u'') = s_B(u') + s_B(u'') - s_A(u') - s_A(u'').$$

Taking u' = -u'' = u produces,  $\forall u \in S^{n-1}$ ,  $s_B(u) + s_B(-u) = s_A(u) + s_A(-u)$ i.e.  $s_B(u) + s_{-B}(u) = s_A(u) + s_{-A}(u)$  i.e.  $s_{B-B}(u) = s_{A-A}(u)$  and B - B = A - A(A and B translate into each other); it follows that  $\exists c \in \mathbb{R}^n$  such that  $A = B + \{c\}$ and  $B = A + \{-c\}$  so that  $A \odot_g B = \{c\}$ .

In case 2. we have that, being  $s_1$  a support function it characterizes a nonempty set  $C \in \mathcal{K}_C^n$  and  $s_C(u) = s_1(u) = s_A(u) - s_B(u)$ ,  $\forall u \in \mathcal{S}^{n-1}$ ; then  $s_A = s_B + s_C = s_{B+C}$  and A = B + C from which (i) is satisfied.

In case 3. we have that  $s_2$  the support function of a nonempty set  $D \in \mathcal{K}_C^n$ and  $s_D(u) = s_B(u) - s_A(u)$ ,  $\forall u \in \mathcal{S}^{n-1}$  so that  $s_B = s_A + s_D = s_{A-D}$  and B = A + D. Defining C = (-1)D (or D = (-1)C) we obtain  $C \in \mathcal{K}_C^n$  with  $s_C(u) = s_{-D}(u) = s_D(-u) = s_B(-u) - s_A(-u) = s_{-B}(u) - s_{-A}(u)$  and (ii) is satisfied.

In case 4. there is no  $C \in \mathcal{K}_C^n$  such that A = B + C (otherwise  $s_1 = s_A - s_B$ is a support function) and there is no  $D \in \mathcal{K}_C^n$  such that B = A + D (otherwise  $s_2 = s_B - s_A$  is a support function); it follows that (i) and (ii) cannot be satisfied and  $A \ominus_a B$  does not exist.

**Proposition 4.** If  $C = A \ominus_g B$  exists, then  $||C|| = \rho_2(A, B)$  and the Steiner points satisfy  $\sigma_C = \sigma_A - \sigma_B$ .

Proof. In fact  $\rho_2(A, B) = ||s_A - s_B||$  and, if  $A \ominus_g B$  exists, then either  $s_C = s_A - s_B$  or  $s_C = s_{-B} - s_{-A}$ ; but  $||s_A - s_B|| = ||s_{-A} - s_{-B}||$  as, changing variable u into -v and recalling that  $s_{-A}(u) = s_A(-u)$ , we have

$$||s_{-A} - s_{-B}|| = \int_{\mathcal{S}^{n-1}} [s_{-A}(u) - s_{-B}(u)]^2 v(du)$$
(5)  
$$= \int_{\mathcal{S}^{n-1}} [s_{A}(-u) - s_{B}(-u)]^2 v(du)$$
  
$$= \int_{\mathcal{S}^{n-1}} [s_{A}(v) - s_{B}(v)]^2 v(-dv) = ||s_{A} - s_{B}||.$$

For the Steiner points, we proceed in a similar manner:

$$\sigma_{C} = \begin{cases} n \int\limits_{\mathcal{S}^{n-1}} u[s_{A}(u) - s_{B}(u)]v(du), \text{ or} \\ n \int\limits_{\mathcal{S}^{n-1}} u[s_{-B}(u) - s_{-A}(u)]v(du) = n \int\limits_{\mathcal{S}^{n-1}} v[s_{A}(v) - s_{B}(v)]v(-dv) \end{cases}$$
(6)

and the result follows from the additivity of the integral.

### 2 The case of compact intervals in $\mathbb{R}^n$

In this section we consider the gH-difference of compact intervals in  $\mathbb{R}^n$ . If n = 1, i.e. for unidimensional compact intervals, the gH-difference always exists. In fact, let  $A = [a^-, a^+]$  and  $B = [b^-, b^+]$  be two intervals; the gH-difference is

$$[a^{-}, a^{+}] \odot_{g} [b^{-}, b^{+}] = [c^{-}, c^{+}] \iff \begin{cases} (i) \\ a^{+} = b^{+} + c^{+} \\ a^{+} = b^{+} + c^{+} \\ b^{-} = a^{-} - c^{+} \\ b^{+} = a^{+} - c^{-} \end{cases}$$

so that  $[a^-, a^+] \ominus_g [b^-, b^+] = [c^-, c^+]$  is always defined by

$$c^{-} = \min\{a^{-} - b^{-}, a^{+} - b^{+}\}, c^{+} = \max\{a^{-} - b^{-}, a^{+} - b^{+}\}$$

i.e.

$$[a,b] \odot_g [c,d] = [\min\{a-c,b-d\}, \max\{a-c,b-d\}].$$

Conditions (i) and (ii) are satisfied simultaneously if and only if the two intervals have the same length and  $c^- = c^+$ . Also, the result is  $\{0\}$  if and only if  $a^- = b^-$  and  $a^+ = b^+$ .

Two simple examples on real compact intervals illustrate the generalization (from [3], p. 8);  $[-1,1] \odot [-1,0] = [0,1]$  as in fact (i) is [-1,0] + [0,1] = [-1,1] but  $[0,0] \odot_g [0,1] = [-1,0]$  and  $[0,1] \odot_g [-\frac{1}{2},1] = [0,\frac{1}{2}]$  satisfy (ii).

Of interest are the symmetric intervals A = [-a, a] and B = [-b, b] with  $a, b \ge 0$ ; it is well known that Minkowski operations with symmetric intervals are such that A - B = B - A = A + B and, in particular, A - A = A + A = 2A. We have  $[-a, a] \ominus_g [-b, b] = [-|a - b|, |a - b|]$ .

As  $S^0 = \{-1, 1\}$  and the support functions satisfy  $s_A(-1) = -a^-$ ,  $s_A(1) = a^+$ ,  $s_B(-1) = -b^-$ ,  $s_B(1) = b^+$ , the same results as before can be deduced by definition (4).

Remark 4. An alternative representation of an interval  $A = [a^-, a^+]$  is by the use of the midpoint  $\hat{a} = \frac{a^- + a^+}{2}$  and the (semi)width  $\overline{a} = \frac{a^+ - a^-}{2}$  and we can write  $A = (\hat{a}, \overline{a}), \ \overline{a} \ge 0$ , so that  $a^- = \hat{a} - \overline{a}$  and  $a^+ = \hat{a} + \overline{a}$ . If  $B = (\hat{b}, \overline{b}), \ \overline{b} \ge 0$  is a second interval, the Minkowski addition is  $A + B = (\hat{a} + \hat{b}, \overline{a} + \overline{b})$  and the gH-difference is obtained by  $A \ominus_g B = (\hat{a} - \hat{b}, |\overline{a} - \overline{b}|)$ . We see immediately that  $A \ominus_g A = \{0\}, \ A = B \iff A \ominus_g B = \{0\}, \ (A + B) \ominus_g B = A$ , but  $A + (B \ominus_g A) = B$  only if  $\overline{a} \le \overline{b}$ .

Let now  $A = \times_{i=1}^{n} A_i$  and  $B = \times_{i=1}^{n} B_i$  where  $A_i = [a_i^-, a_i^+]$ ,  $B_i = [b_i^-, b_i^+]$  are real compact intervals ( $\times_{i=1}^{n}$  denotes the cartesian product).

In general, considering  $D = \times_{i=1}^{n} (A_i \odot_g B_i)$ , we may have  $A \odot_g B \neq D$  e.g.  $A \odot_g B$  may not exist as for the example  $A_1 = [3,6], A_2 = [2,6], B_1 = [5,10], B_2 = [7,9]$  for which  $(A_1 \odot_g B_1) = [-4,-2], (A_2 \odot_g B_2) = [-5,-3], D = [-4,-2] \times [-5,-3]$  and  $B+D = [1,8] \times [2,6] \neq A, A+(-1)D = [5,10] \times [5,11] \neq B.$  But if  $A \odot_g B$  exists, then equality will hold. In fact, consider the support function of A (and similarly for B), defined by

$$s_A(u) = \max_x \{ \langle u, x \rangle \, | a_i^- \le x_i \le a_i^+ \}, \, u \in \mathcal{S}^{n-1}; \tag{7}$$

it can be obtained simply by  $s_A(u) = \sum_{u_i > 0} u_i a_i^+ + \sum_{u_i < 0} u_i a_i^-$  as the box-constrained maxima of the linear objective functions  $\langle u, x \rangle$  above are attained at vertices  $\hat{x}(u) = (\hat{x}_1(u), ..., \hat{x}_i(u), ..., \hat{x}_n(u))$  of A, i.e.  $\hat{x}_i(u) \in \{a_i^-, a_i^+\}, i = 1, 2, ..., n$ . Then

$$s_A(u) - s_B(u) = \sum_{u_i > 0} u_i(a_i^+ - b_i^+) + \sum_{u_i < 0} u_i(a_i^- - b_i^-)$$
(8)

and, being  $s_{-A}(u) = s_A(-u) = -\sum_{u_i < 0} u_i a_i^+ - \sum_{u_i > 0} u_i a_i^-$ ,

$$s_{-B}(u) - s_{-A}(u) = \sum_{u_i > 0} u_i(a_i^- - b_i^-) + \sum_{u_i < 0} u_i(a_i^+ - b_i^+).$$
(9)

From the relations above, we deduce that

$$A \odot_g B = C \iff \begin{cases} (i) \begin{cases} C = \times_{i=1}^n [a_i^- - b_i^-, a_i^+ - b_i^+] \\ \text{provided that } a_i^- - b_i^- \le a_i^+ - b_i^+, \forall i \\ \\ \text{or } (ii) \begin{cases} C = \times_{i=1}^n [a_i^+ - b_i^+, a_i^- - b_i^-] \\ \text{provided that } a_i^- - b_i^- \ge a_i^+ - b_i^+, \forall i \end{cases} \end{cases}$$

and the gH-difference  $A \ominus_g B$  exists if and only if one of the two conditions are satisfied:

case (i) 
$$a_i^- - b_i^- \le a_i^+ - b_i^+, i = 1, 2, ..., n$$
  
case (ii)  $a_i^- - b_i^- \ge a_i^+ - b_i^+, i = 1, 2, ..., n$ 

#### Examples:

<u>1. case (i)</u>:  $A_1 = [5, 10], A_2 = [1, 3], B_1 = [3, 6], B_2 = [2, 3]$  for which  $(A_1 \odot_g B_1) = [2, 4], (A_2 \odot_g B_2) = [-1, 0]$  and  $A \odot_g B = C = [2, 4] \times [-1, 0]$  exists with  $B + C = A, A + (-1)C \neq B$ .

<u>2. case (ii)</u>:  $A_1 = [3,6], A_2 = [2,3], B_1 = [5,10], B_2 = [1,3]$  for which  $(A_1 \odot_g B_1) = [-4,-2], (A_2 \odot_g B_2) = [0,1]$  and  $A \odot_g B = C = [-4,-2] \times [0,1]$  exists with  $B + C \neq A, A + (-1)C = B$ .

3. case (i) + (ii):  $A_1 = [3, 6], A_2 = [2, 3], B_1 = [5, 8], B_2 = [3, 4]$  for which  $(A_1 \odot_g B_1) = [-2, -2] = \{-2\}, (A_2 \odot_g B_2) = [-1, -1] = \{-1\}$  and  $A \odot_g B = C = \{(-2, -1)\}$  exists with B + C = A and A + (-1)C = B.

We end this section with a comment on the simple interval equation

$$A + X = B \tag{10}$$

where  $A = [a^-, a^+]$ ,  $B = [b^-, b^+]$  are given intervals and  $X = [x^-, x^+]$  is an interval to be determined satisfying (10). We have seen that, for unidimensional intervals, the gH-difference always exists. Denote by  $l(A) = a^+ - a^-$  the length of interval A. It is well known from classical interval arithmetic that an interval

X satisfying (10) exists only if  $l(B) \ge l(A)$  (in Minkowski arithmetic we have  $l(A + X) \ge \max\{l(A), l(X)\}$ ); in fact, no X exists with  $x^- \le x^+$  if l(B) < l(A) and we cannot solve (10) unless we interpret it as B - X = A. If we do so, we get

case 
$$l(B) \le l(A)$$
:   

$$\begin{cases} a^{-} + x^{-} = b^{-} & x^{-} = b^{-} - a^{-} \\ a^{+} + x^{+} = b^{+} & \text{i.e.} & x^{-} = b^{-} - a^{-} \\ x^{-} = b^{-} - a^{-} & x^{-} = b^{+} - a^{+} \\ b^{+} - x^{-} = a^{+} & \text{i.e.} & x^{+} = b^{-} - a^{-} \end{cases}$$

We then obtain that  $X = B \odot_g A$  is the unique solution to (10) and it always exists, i.e.

**Proposition 5.** Let  $A, B \in \mathcal{K}_C(\mathbb{R})$ ; the gH-difference  $X = B \odot_g A$  always exists and either  $A + (B \odot_g A) = B$  or  $B - (B \odot_g A) = A$ .

From property 6) of Proposition 7, a similar result is true for equation A + X = B with  $A, B \in \mathcal{K}_C(\mathbb{R}^n)$  but for n > 1 the gH-difference may non exist.

## 3 gH-difference of fuzzy numbers

A general fuzzy set over a given set (or space)  $\mathbb{X}$  of elements (the universe) is usually defined by its membership function  $\mu : \mathbb{X} \longrightarrow \mathbb{T} \subseteq [0, 1]$  and a fuzzy (sub)set u of  $\mathbb{X}$  is uniquely characterized by the pairs  $(x, \mu_u(x))$  for each  $x \in \mathbb{X}$ ; the value  $\mu_u(x) \in [0, 1]$  is the membership grade of x to the fuzzy set u. We will consider particular fuzzy sets, called fuzzy numbers, defined over  $\mathbb{X} = \mathbb{R}$ having a particular form of the membership function. Let  $\mu_u$  be the membership function of a fuzzy set u over  $\mathbb{X}$ . The support of u is the (crisp) subset of points of  $\mathbb{X}$  at which the membership grade  $\mu_u(x)$  is positive:  $supp(u) = \{x | x \in \mathbb{X}, \mu_u(x) > 0\}$ . For  $\alpha \in ]0, 1]$ , the  $\alpha$ -level cut of u (or simply the  $\alpha - cut$ ) is defined by  $[u]_{\alpha} = \{x | x \in \mathbb{X}, \mu_u(x) \ge \alpha\}$  and for  $\alpha = 0$  (or  $\alpha \to +0$ ) by the closure of the support  $[u]_0 = cl\{x | x \in \mathbb{X}, \mu_u(x) > 0\}$ .

A well-known property of the *level* – *cuts* is  $[u]_{\alpha} \subseteq [u]_{\beta}$  for  $\alpha > \beta$  (i.e. they are nested).

A particular class of fuzzy sets u is when the support is a convex set and the membership function is quasi-concave i.e.  $\mu_u((1-t)x'+tx'') \ge \min\{\mu_u(x'), \mu_u(x'')\}$ for every  $x', x'' \in supp(u)$  and  $t \in [0, 1]$ . Equivalently,  $\mu_u$  is quasi-concave if the level sets  $[u]_{\alpha}$  are convex sets for all  $\alpha \in [0, 1]$ . A third property of the fuzzy numbers is that the level-cuts  $[u]_{\alpha}$  are closed sets for all  $\alpha \in [0, 1]$ .

By using these properties, the space  $\mathcal{F}$  of (real unidimensional) fuzzy numbers is structured by an addition and a scalar multiplication, defined either by the level sets or, equivalently, by the Zadeh extension principle. Let  $u, v \in \mathcal{F}$  have membership functions  $\mu_u, \mu_v$  and  $\alpha - cuts [u]_{\alpha}, [v]_{\alpha}, \alpha \in [0, 1]$  respectively. The addition  $u + v \in \mathcal{F}$  and the scalar multiplication  $ku \in \mathcal{F}$  have level cuts

$$[u+v]_{\alpha} = [u]_{\alpha} + [v]_{\alpha} = \{x+y|x\in[u]_{\alpha}, \ y\in[v]_{\alpha}\}$$
(11)

$$[ku]_{\alpha} = k[u]_{\alpha} = \{kx | x \in [u]_{\alpha}\}.$$
(12)

In the fuzzy or in the interval arithmetic contexts, equation u = v + w is not equivalent to w = u - v = u + (-1)v or to v = u - w = u + (-1)w and this has motivated the introduction of the following Hukuhara difference ([3], [5]). The generalized Hukuhara difference is (implicitly) used by Bede and Gal (see [1]) in their definition of generalized differentiability of a fuzzy-valued function.

**Definition 2.** Given  $u, v \in \mathcal{F}$ , the *H*-difference is defined by  $u \odot v = w \iff u = v + w$ ; if  $u \odot v$  exists, it is unique and its  $\alpha$ -cuts are  $[u \odot v]_{\alpha} = [u_{\alpha}^{-} - v_{\alpha}^{-}, u_{\alpha}^{+} - v_{\alpha}^{+}]$ . Clearly,  $u \odot u = \{0\}$ .

The Hukuhara difference is also motivated by the problem of inverting the addition: if x, y are crisp numbers then (x+y) - y = x but this is not true if x, y are fuzzy. It is possible to see that (see [2]), if u and v are fuzzy numbers (and not in general fuzzy sets), then  $(u+v) \odot v = u$  i.e. the H-difference inverts the addition of fuzzy numbers.

The gH-difference for fuzzy numbers can be defined as follows:

**Definition 3.** Given  $u, v \in \mathcal{F}$ , the gH-difference is the fuzzy number w, if it exists, such that

$$u \ominus_g v = w \Longleftrightarrow \begin{cases} (i) & u = v + w \\ or (ii) & v = u + (-1)w \end{cases}$$
(13)

If  $u \odot_g v$  exists, its  $\alpha$  - cuts are given by  $[u \odot_g v]_{\alpha} = [\min\{u_{\alpha}^- - v_{\alpha}^-, u_{\alpha}^+ - v_{\alpha}^+\}, \max\{u_{\alpha}^- - v_{\alpha}^-, u_{\alpha}^+ - v_{\alpha}^+\}]$  and  $u \odot v = u \odot_g v$  if  $u \odot v$  exists. If (i) and (ii) are satisfied simultaneously, then w is a crisp number. Also,  $u \odot_g u = u \odot u = \{0\}$ .

A definition of  $w = u \odot_g v$  for multidimensional fuzzy numbers can be obtained in terms of support functions in a way similar to (4)

$$s_w(p;\alpha) = \begin{cases} s_u(p;\alpha) - s_v(p;\alpha) & \text{in case } (i) \\ s_{(-1)v}(p;\alpha) - s_{(-1)u}(p;\alpha) & \text{in case } (ii) \end{cases}, \ \alpha \in [0,1]$$
(14)

where, for a fuzzy number u, the support functions are considered for each  $\alpha - cut$ and defined to characterize the (compact)  $\alpha - cuts [u]_{\alpha}$ :

$$s_u : \mathbb{R}^n \times [0, 1] \longrightarrow \mathbb{R}$$
 defined by  
 $s_u(p; \alpha) = \sup\{\langle p, x \rangle | x \in [u]_{\alpha}\}$  for each  $p \in \mathbb{R}^n, \alpha \in [0, 1].$ 

In the unidimensional fuzzy numbers, the conditions for the definition of  $w = u \ominus_g v$  are

$$[w]_{\alpha} = [w_{\alpha}^{-}, w_{\alpha}^{+}] = [u]_{\alpha} \odot_{g} [v]_{\alpha} : \begin{cases} w_{\alpha}^{-} = \min\{u_{\alpha}^{-} - v_{\alpha}^{-}, u_{\alpha}^{+} - v_{\alpha}^{+}\} \\ w_{\alpha}^{+} = \max\{u_{\alpha}^{-} - v_{\alpha}^{-}, u_{\alpha}^{+} - v_{\alpha}^{+}\} \end{cases}$$
(15)

provided that  $w_{\alpha}^{-}$  is nondecreasing,  $w_{\alpha}^{+}$  is nonincreasing and  $w_{\alpha}^{-} \leq w_{\alpha}^{+}$ .

If  $u \ominus_g v$  is a proper fuzzy number, it has the same properties illustrated in section 1. for intervals.

**Proposition 6.** If  $u \ominus_g v$  exists, it is unique and has the following properties: 1)  $u \ominus_g u = 0$ ; 2)  $(u + v) \ominus_g v = u$ ; () u = 0; ()

3) If  $u \ominus_g v$  exists then also  $(-v) \ominus_g (-u)$  does and  $\{0\} \ominus_g (u \ominus_g v) = (-v) \ominus_g (-u);$ 4)  $(u-v) + v = w \iff u - v = w \ominus_g v;$ 5)  $(u \ominus_g v) = (v \ominus_g u) = w$  if and only if  $(w = \{0\} and u = v);$ 

6) If  $v \ominus_g u$  exists then either  $u + (v \ominus_g u) = u$  or  $v - (v \ominus_g u) = u$  and if both

equalities hold then  $v \ominus_g u$  is a crisp set.

If the gH-differences  $[u]_{\alpha} \ominus_g [v]_{\alpha}$  do not define a proper fuzzy number, we can use the nested property and obtain a proper fuzzy number by

$$[u \widetilde{\ominus}_g v]_{\alpha} := \bigcup_{\beta \ge \alpha} ([u]_{\beta} \ominus_g [v]_{\beta}); \tag{16}$$

As each gH-difference  $[u]_{\beta} \ominus_g [v]_{\beta}$  exists for  $\beta \in [0, 1]$  and (16) defines a proper fuzzy number, it follows that  $u \ominus_g v$  can be considered as a generalization of Hukuhara difference for fuzzy numbers, existing for any u, v. A second possibility for a gH-difference of fuzzy numbers may be obtained following a suggestion by Kloeden and Diamond ([3]) and defining  $z = u \ominus_g v$  to be the fuzzy number whose  $\alpha - cuts$  are as near as possible to the gH-differences  $[u]_{\alpha} \ominus_g [v]_{\alpha}$ , for example by minimizing the functional ( $\omega_{\alpha} \geq 0$  and  $\gamma_{\alpha} \geq 0$  are weighting functions)

$$G(z|u,v) = \int_{0}^{1} (\omega_{\alpha} \left[ z_{\alpha}^{-} - (u \ominus_{g} v)_{\alpha}^{-} \right]^{2} + \gamma_{\alpha} \left[ z_{\alpha}^{+} - (u \ominus_{g} v)_{\alpha}^{+} \right]^{2}) d\alpha$$

such that  $z_{\alpha}^{-}\uparrow$ ,  $z_{\alpha}^{+}\downarrow$ ,  $z_{\alpha}^{-}\leq z_{\alpha}^{+}$   $\forall \alpha \in [0,1]$ .

A discretized version of G(z|u, v) can be obtained by choosing a partition  $0 = \alpha_0 < \alpha_1 < \ldots < \alpha_N = 1$  of [0, 1] and defining the discretized G(z|u, v) as

$$G_N(z|u,v) = \sum_{i=0}^N \omega_i \left[ z_i^- - (u \ominus_g v)_i^- \right]^2 + \gamma_i \left[ z_i^+ - (u \ominus_g v)_i^+ \right]^2;$$

we minimize  $G_N(z|u, v)$  with the given data  $(u \odot_g v)_i^- = \min\{u_{\alpha_i}^- - v_{\alpha_i}^-, u_{\alpha_i}^+ - v_{\alpha_i}^+\}$ and  $(u \odot_g v)_i^+ = \max\{u_{\alpha_i}^- - v_{\alpha_i}^-, u_{\alpha_i}^+ - v_{\alpha_i}^+\}$ , subject to the constraints  $z_0^- \le z_1^- \le \dots \le z_N^- \le z_N^+ \le z_{N-1}^+ \le \dots \le z_0^+$ . We obtain a linearly constrained least squares minimization of the form

$$\min_{z \in \mathbb{R}^{2N+2}} (z-w)^T D^2 (z-w) \text{ s.t. } Ez \ge 0$$

where  $z = (z_0^-, z_1^-, ..., z_N^-, z_N^+, z_{N-1}^+, ..., z_0^+), w_i^- = (u \odot_g v)_i^-, w_i^+ = (u \odot_g v)_i^+, w_i^- = (w_0^-, w_1^-, ..., w_N^-, w_{N-1}^+, ..., w_0^+), D = diag\{\sqrt{\omega_0}, ..., \sqrt{\omega_N}, \sqrt{\gamma_N}, ..., \sqrt{\gamma_0}\}$ and E is the (N, N+1) matrix

$$E = \begin{bmatrix} -1 \ 1 \ 0 \ \dots \ \dots \ 0 \\ 0 \ -1 \ 1 \ 0 \ \dots \ 0 \\ \dots \ \dots \ \dots \\ 0 \ 0 \ \dots \ \dots \ \dots \ \dots \ \dots \\ 0 \ 0 \ \dots \ \dots \ -1 \ 1 \end{bmatrix}$$

which can be solved by standard efficient procedures (see the classical book [6], ch. 23). If, at solution  $z^*$ , we have  $z^* = w$ , then we obtain the gH-difference as defined in (13).

# 4 Generalized division

An idea silmilar to the gH-difference can be used to introduce a division of real intervals and fuzzy numbers. We consider here only the case of real compact intervals  $A = [a^-, a^+]$  and  $B = [b^-, b^+]$  with  $b^- > 0$  or  $b^+ < 0$  (i.e.  $0 \notin B$ ).

The interval  $C = [c^-, c^+]$  defining the multiplication C = AB is given by

$$c^- = \min\{a^-b^-, a^-b^+, a^+b^-, a^+b^+\} \ , \ c^+ = \max\{a^-b^-, a^-b^+, a^+b^-, a^+b^+\}$$

and the multiplicative "inverse" (it is not the inverse in the algebraic sense) of an interval B is defined by  $B^{-1} = [\frac{1}{b^+}, \frac{1}{b^-}]$ ; we define the generalized division (g-division)  $\div_g$  as follows:

$$A \div_g B = C \iff \begin{cases} (i) & A = BC \\ \text{or } (ii) & B = AC^{-1} \end{cases}$$

If both cases (i) and (ii) are valid, we have  $CC^{-1} = C^{-1}C = \{1\}$ , i.e.  $C = \{\hat{c}\}, C^{-1} = \{\frac{1}{\hat{c}}\}$  with  $\hat{c} \neq 0$ . It is easy to see that  $A \div_g B$  always exists and is unique for given  $A = [a^-, a^+]$  and  $B = [b^-, b^+]$  with  $0 \notin B$ . It is easy to see that it can be obtained by the following rules:

Case 1. If  $(a^- \le a^+ < 0 \text{ and } b^- \le b^+ < 0)$  or  $(0 < a^- \le a^+ \text{ and } 0 < b^- \le b^+)$  then

$$c^{-} = \min\{\frac{a^{-}}{b^{-}}, \frac{a^{+}}{b^{+}}\} \ge 0, \ c^{+} = \max\{\frac{a^{-}}{b^{-}}, \frac{a^{+}}{b^{+}}\} \ge 0;$$

Case 2. If  $(a^- \le a^+ < 0$  and  $0 < b^- \le b^+)$  or  $(0 < a^- \le a^+$  and  $b^- \le b^+ < 0)$  then

$$c^{-} = \min\{\frac{a^{-}}{b^{+}}, \frac{a^{+}}{b^{-}}\} \le 0, \ c^{+} = \max\{\frac{a^{-}}{b^{+}}, \frac{a^{+}}{b^{-}}\} \le 0;$$

Case 3. If  $(a^- \le 0, a^+ \ge 0 \text{ and } b^- \le b^+ < 0)$  then

$$e^{-} = \frac{a^{-}}{b^{-}} \le 0, \ e^{+} = \frac{a^{+}}{b^{-}} \ge 0;$$

Case 4. If  $(a^{-} \le 0, a^{+} \ge 0 \text{ and } 0 < b^{-} \le b^{+})$  then

$$c^{-} = \frac{a^{-}}{b^{+}} \le 0, \ c^{+} = \frac{a^{+}}{b^{+}} \ge 0.$$

Remark 5. If  $0 \in ]b^-, b^+[$  the g-division is undefined; for intervals  $B = [0, b^+]$  or  $B = [b^-, 0]$  the division is possible but obtaining unbounded results C of the form  $C = ]-\infty, c^+]$  or  $C = [c^-, +\infty[$ : we work with  $B = [\varepsilon, b^+]$  or  $B = [b^-, \varepsilon]$  and we obtain the result by the limit for  $\varepsilon \longrightarrow 0^+$ . Example: for  $[-2, -1] \div_g [0, 3]$  we consider  $[-2, -1] \div_g [\varepsilon, 3] = [c_{\varepsilon}^-, c_{\varepsilon}^+]$  with (case 2.)  $c_{\varepsilon}^- = \min\{\frac{-2}{3}, \frac{-1}{\varepsilon}\}$  and  $c_{\varepsilon}^+ = \max\{\frac{-2}{\varepsilon}, \frac{-1}{3}\}$  and obtain the result  $C = [-\infty, -\frac{1}{3}]$  at the limit  $\varepsilon \longrightarrow 0^+$ .

The following properties are immediate.

**Proposition 7.** For any  $A = [a^-, a^+]$  and  $B = [b^-, b^+]$  with  $0 \notin B$ , we have (here 1 is the same as  $\{1\}$ ): 1.  $B \div_g B = 1, B \div_g B^{-1} = \{b^-b^+\} (= \{\hat{b}^2\} \text{ if } b^- = b^+ = \hat{b});$ 2.  $(AB) \div_B - A;$ 

$$2. \qquad (AB) \div_g B = A;$$

3.  $1 \div_g B = B^{-1} \text{ and } 1 \div_g B^{-1} = B.$ 

In the case of fuzzy numbers  $u, v \in \mathcal{F}$  having membership functions  $\mu_u, \mu_v$ and  $\alpha - cuts \ [u]_{\alpha} = [u_{\alpha}^-, u_{\alpha}^+], \ [v]_{\alpha} = [v_{\alpha}^-, v_{\alpha}^+], \ 0 \notin [v]_{\alpha} \ \forall \alpha \in [0, 1], \ \text{the } g\text{-division} \\ \div_g \text{ can be defined as the operation that calculates the fuzzy number } w = u \div_g v \in \mathcal{F} \text{ having level cuts } [w]_{\alpha} = [w_{\alpha}^-, w_{\alpha}^+] \ (\text{here } [w]_{\alpha}^{-1} = [\frac{1}{w_{\alpha}^+}, \frac{1}{w_{\alpha}^-}]):$ 

$$[u]_{\alpha} \div_{g} [v]_{\alpha} = [w]_{\alpha} \iff \begin{cases} (i) \quad [u]_{\alpha} = [v]_{\alpha}[w]_{\alpha} \\ \text{or} \ (ii) \quad [v]_{\alpha} = [u]_{\alpha}[w]_{\alpha}^{-1} \end{cases},$$

provided that w is a proper fuzzy number.

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